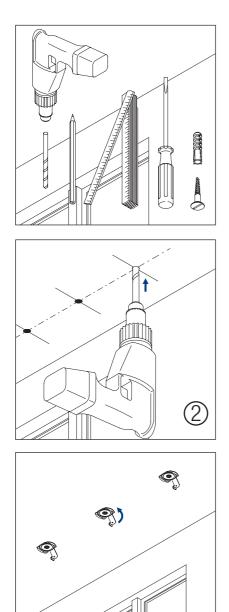
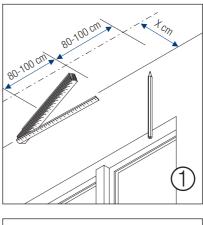


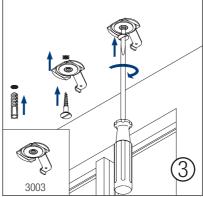
Fitting sheet (ceiling)

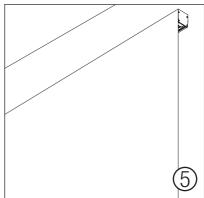
Supplied by



4





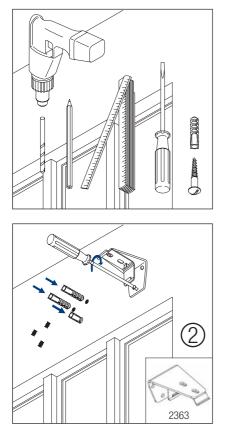


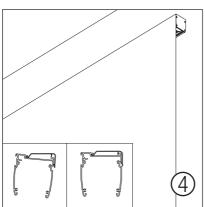


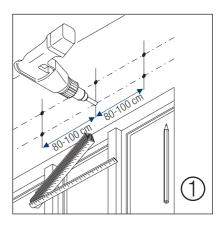


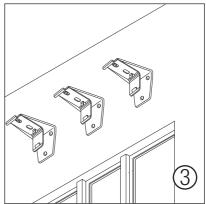
Fitting sheet (wall)

Supplied by







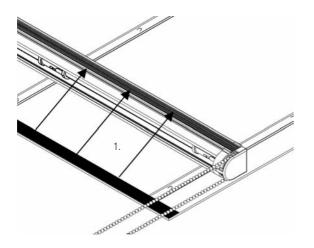






Fitting sheet

Attaching the fabric to the headrail

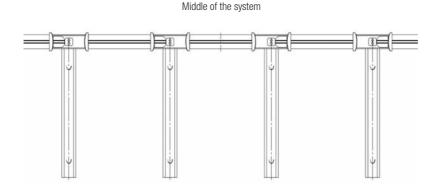


Lay the fabric on his front side and lay the system on the fabric like shown.

1. Reverse the fabric and fix the fabric on the hook tape.

Afterwards, turn the profile on the top of the profile to align the shells.

Aligning the shell with the loop tape or rings



Align the shells according to the position of the loop tapes. The arrows on the shells must be in line with the loop tape / rings.

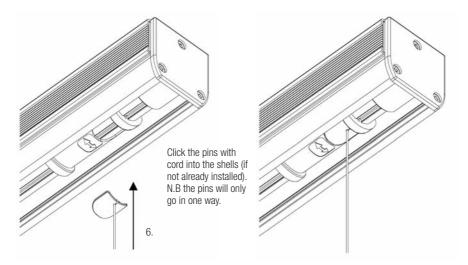




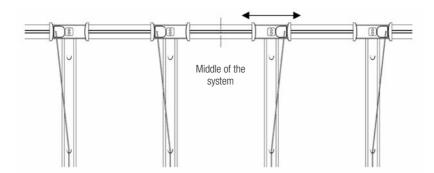
Fitting sheet

Supplied by

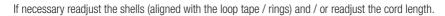
Connecting the pins and cord



Adjusting the shells



Once the system has been installed check that the cord is winding neatly onto the spools.







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SILENTGLISS SPAR

Silent Gliss® 2350

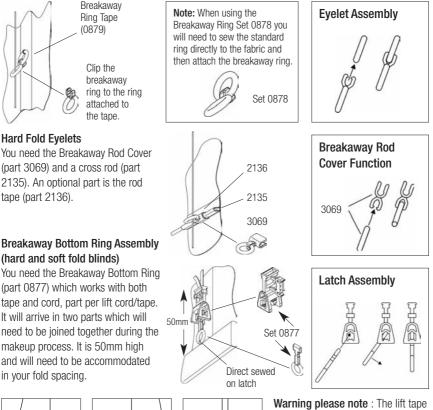
Fitting sheet

Roman Blind Child Safety Parts - Assembly Instructions

Please find below sewing instructions for the new Silent Gliss Roman blind child safety parts. These can only be used with Silent Gliss Roman blind headrail systems. The safety eyelet and bottom ring assemblies must be used in conjunction with each other.

Soft Fold Eyelets

You need either the Breakaway Ring Tape (part 0879) or a quantity of Breakaway Ring Sets (Part 0878). The safety sets will arrive in two parts and you will need to join the rings together during the makeup process.



Warning please note : The lift tape of cord should be taut against the rear of the fabric when the blind is in the fully lowered position. The tapes and cord should always be central within the 0877 breakaway device.









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Silent Gliss® 2350

Fitting sheet



If the system winds up as shown in the diagram when the up button is switched, then the wiring is correct. If not then the two switch lives must be reversed.

The cords must always be wound up to the front of the system. Otherwise the fabric will be pulled backwards.

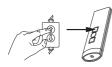
Set Limit Positions using 0997 Setting lead

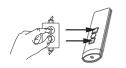
- Motors are delivered to SGGB in 'Programming' mode
- Motor limits are then set approximately during production (as normal)
- Limits can be reset on site either by 0997 test lead or by 9940 series wireless switches or handsets (wireless motors only)

- A 0997 test lead will be required if non radio control type

 Please note when adjusting or re-setting limits both the up and down limits must be reset individual limits cannot be set independently

Changing/Erasing Limit Positions



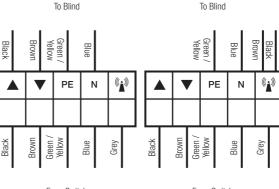




approx.

5 sec.





From Switch

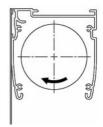
Connections for non integrated motor

From Switch

Connections for integrated motor

- Drive blind to approximately mid position - thereby determining the direction of movement of the blind on the switch (you must allow at least 30cm of movement to the nearest limit setting position).
 For integrated motors now unplug from the supply for 1 - 2 seconds and then re-connect.
- Press the up and down buttons on the test lead (or handset) together, after approx. 5 sec. motor will respond with a short up and down movement.
- Limits are erased. Motor is now in limit setting mode







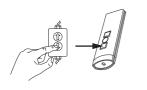
Fitting sheet

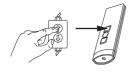


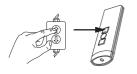
Setting Limit Positions - Limits can be set in either direction at this stage the instructions below start with the setting the down limit first.

STOP

STOP









 Press and hold the up button until motor stops automatically (approx 30 cm movement).

 Hold the down button until motor 'jolts' and increases speed then continue pressing down button until blind is at required position.

> (To get to an accurate limit position release the button and pulse in the same direction with the same button in small movements).

Release the up button

Lower position is set

 Hold the up button until motor 'jolts' and increases speed then continue pressing up button until blind is at required position.

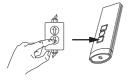
> (To get to an accurate limit position release the button and pulse in the same direction with the same button in small movements).

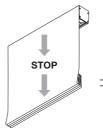
 Press and hold the down button until motor stops automatically (approx 30 cm movement).

Release the down button.

> Both limits are set













www.silentgliss.co.uk

Silent Gliss Limited Pyramid Business Park Poorhole Lane Broadstairs Kent CT10 2PT

Telephone: 01843 863571 Fax: 01843 864503 info@silentgliss.co.uk

